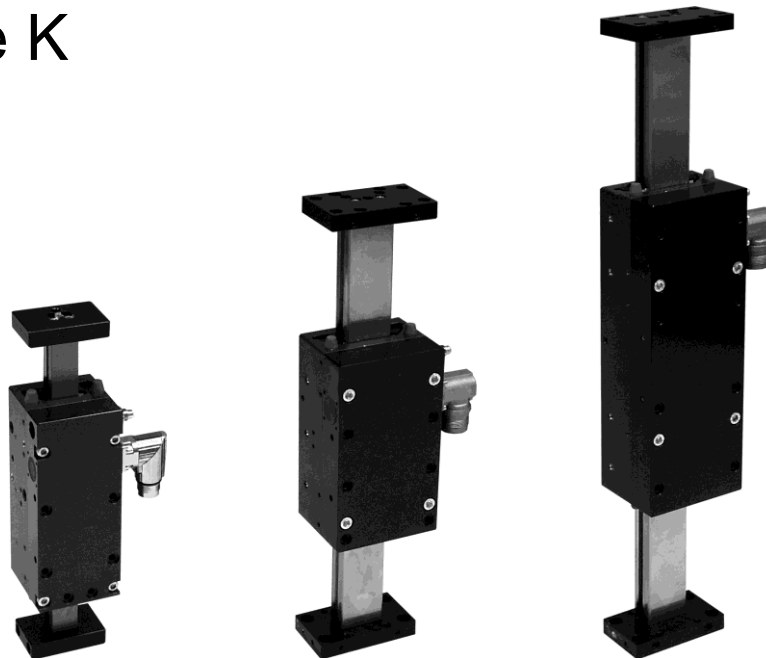


LINEAR MOTOR DRIVE

MLD type K



Dear Customer,

Congratulations on choosing a SCHUNK product. By choosing SCHUNK, you have opted for the highest precision, top quality and best service.

You are going to increase the process reliability of your production and achieve best machining results – to the customer's complete satisfaction.

SCHUNK products are inspiring.

Our detailed assembly and operation manual will support you.

Do you have further questions? You may contact us at any time – even after purchase. You can reach us directly at the mentioned addresses in the last chapter of these instructions.

Kindest Regards,

Your SCHUNK GmbH & Co. KG
Precision Workholding Systems
Bahnhofstr. 106 - 134
D-74348 Lauffen/ Neckar

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1. Safety

1.1. Symbol key



This symbol is used whenever non-compliance may lead to dangers for persons.



This symbol is used whenever non-compliance may lead to damage to the product.



This symbol alerts you to important information concerning the product and its handling.

1.2. Appropriate use

Linear motor drives MLD type K are used exclusively for the purpose of transmitting linear movements using a directly driven drive module.



The axis is especially suited for applications for which very high dynamics are required.

1.3. General safety

- The objective of this operating manual is to provide qualified persons with the information necessary to enable them to carry out maintenance work on a linear motor drive MLD type K themselves.

1.4. Safety notes

1. Dangerous situations may arise in conjunction with the unit if, for example:
 - The linear motor drive is not used, installed or maintained properly.
 - The linear motor drive is used for purposes other than the intended appropriate use.
 - The EC Machinery Directive, the accident prevention regulations, the VDE directives, or the safety and installation notes are not observed.
2. The linear motor drive MLD type K may only be installed, commissioned and maintained by suitably trained specialist personnel based on these instructions.

3. The linear motor drive MLD type K is equipped with protective equipment for your safety. Nevertheless, danger may emanate from this drive if it is operated by insufficiently trained personnel or used for tasks that are not permitted.
4.  The secondary parts integrated in the linear motor drive MLD type K are high-performance permanent magnets. These can cause injuries to persons with implanted medical devices such as pacemakers or hearing aids, or implanted medical devices can cause malfunctions. Even when the linear motor drive is switched off, these persons must not stay close to the drive. Electronic modules, storage media, precision elements and other magnetically interactive objects can be damaged.
5. As a general rule, all work on the drives and control units may be performed only while they are shut down. There must not be any voltage present.
6.  If possible, avoid running measurement cables directly next to electric cables.
7. Before starting any assembly/disassembly or repair work, allow the linear motor drive to cool down.

1.5. Protection against dangerous movements

As a general rule, the linear motor drives may only be operated with additional safety devices which are not included in the scope of delivery. Dangerous movements can result when errors occur in controlling the drives. The drive components are monitored in a way that malfunctions can be largely excluded.

However, for reasons of personal safety, risk of injury and risk of property damage, you should not rely on this fact alone. Until the integrated safety features become effective, inaccurate drive movements must be expected.

Possible causes for control errors:

- Incorrect cabling or wiring
- Defective components
- Software errors
- Operating errors
- Removal of safety devices
- Sensor and signal transmitter errors
- Entry of incorrect parameters prior to start-up

1.6. Ambient and operating conditions

To ensure problem-free operation, certain ambient and operating conditions must be provided.

- (1) Ambient temperature: 10°C to 40°C
- (2) Permitted medium: Filtered compressed air (10 µm), dry, lubricated or non-lubricated
- (3) The drive must be protected against the following:
 - Exposure to direct sunlight or heat
 - Contamination due to chips, dust and other particles
 - Corrosive gases
 - Vibrations
 - Shock
 - Moisture
 - Oleaginous and acidic environments

If the components are to be used in adverse ambient conditions (e.g. honing oil or other corrosive media), consult with us.

1.7. Modifications to the linear motor drive

Modifications to the linear motor drive MLD type K and/or the attachment of third-party components can compromise the operational safety of the drive. This applies in particular to changes made to safety-relevant parts. If modifications are made to the linear motor drive, SCHUNK will not accept any warranty claims.

1.8. Other relevant documentation

Other relevant documentation with CD: Commissioning of Indradrive (German/English), GAS order no. 315016



2. Warranty

The warranty period is 24 months from the delivery date to the production facility, provided the product is used as intended in one-shift operation and the prescribed maintenance and lubrication intervals have been observed. As a general rule, parts touching the workpiece and wearing parts are not part of the warranty. Also observe our general terms and conditions. They are available on our website at www.de.schunk.com in the "Service" section under "Terms of Sales and Delivery".

3. Scope of delivery

The standard scope of delivery comprises: The ordered version of the linear motor drive MLD type K, including start-up CD and operating manual.

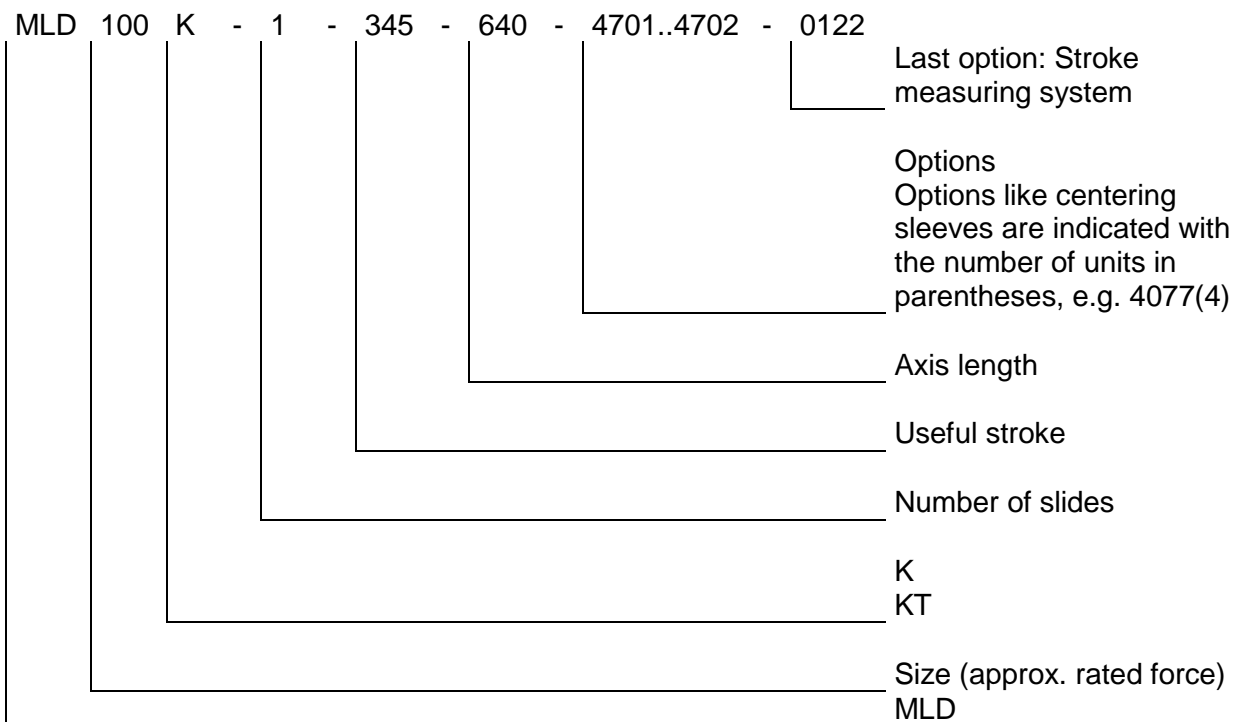


4. Product description

4.1. Overview of types

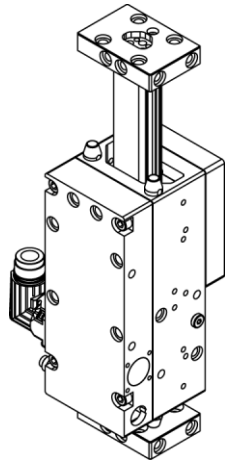
The linear motor drives are distinguished based on their type designation and size:

MLD 100K-1-345-640-4701-4701-.....4733(4)-0122

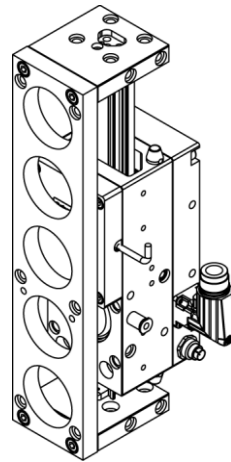


SCHUNK GmbH & Co.KG strives to constantly improve its products. Therefore it is important that you include the material number and serial number in all inquiries and spare part orders.

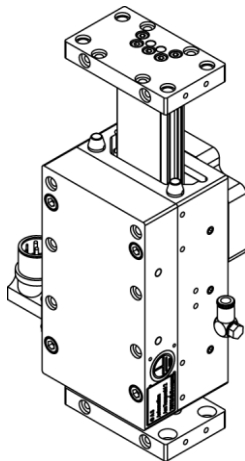
MLD 50 K



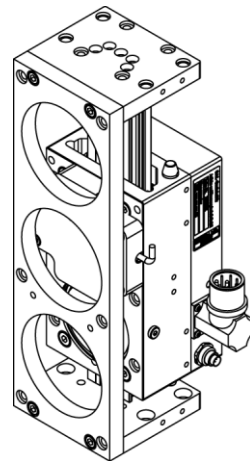
MLD 50 KT



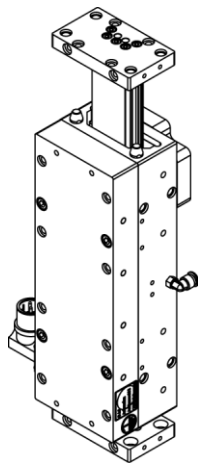
MLD 100 K



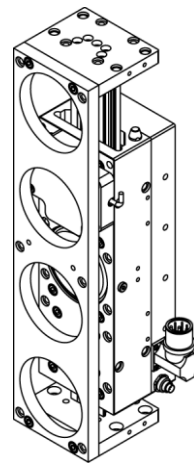
MLD 100 KT



MLD 200 K



MLD 200 KT





4.2. Functional principle

The linear motor drive MLD type K is a directly driven drive module for linear movements. The driving force is transmitted directly to the slide without any mechanical transmission elements. The axis is especially suited for applications for which very high dynamics are required.

The overall concept of the linear motor drive is characterized by its extremely compact design. Thanks to the good guidance of the slide and the light-weight design of the axis, the drive reaches very high speeds, accelerations and repeat accuracies.

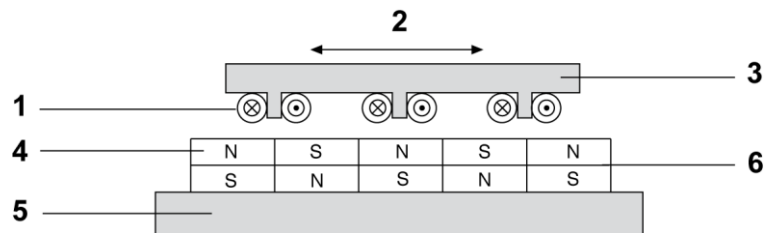


Figure 1: Functional principle of linear motor drive MLD type K

- (1) Copper coil
- (2) Directions of movement
- (3) Primary part
- (4) Permanent magnets
- (5) Iron mount
- (6) Secondary part

You can manipulate the driving force, acceleration and speed of the slide by regulating the phase and the amplitude of the electrical current applied at the primary part (item 3).

As standard, a magnetic measuring system, which is integrated in the axis, is used to determine the current position of the drive.

Optical or absolute stroke measuring systems are available as options.

5. Technical data

Motor size		MLD 50 K (T)	MLD 100 K (T)	MLD 200 K (T)
Rated force ^{*2}	(N)	45	74	136
Maximum force ^{*1}	(N)	125	250	500
Repeat accuracy	(mm)	±0.01	±0.01	±0.01
Max. continuous current at standstill	(A _{eff})	1.1	2.1	3.8
Maximum current	(A _{eff})	4.1	8.1	16.2
Coil resistance at 25°C	(Ohm)	16.4	7.1	3.5
Test voltage	(V)	2000	2000	2000
Max. surface and ambient temperature	(°C)	70/40	70/40	70/40

Table 1: Technical data of the linear motor drive

*¹) depending on control type

*²) depending on installation situation (heat dissipation)

Should you require additional technical data, please refer to our catalog. The respective latest version is valid (as stipulated in the General Terms and Conditions document, section 2.3).

6. Transport and storage

6.1. Transport

The linear motor drives MLD type K are precision drives. The packaging must protect the drive from all external effects (such as mechanical shocks and humidity).

6.2. Storage

Store the product in a clean, dry environment. Ambient temperature: 15–40°C.
No condensation permitted!

7. Commissioning

7.1. Installation preparation

7.1.1. Safety notes prior to use



Danger to life due to strong magnetic fields even in a shut-down state.

The secondary parts integrated in the linear motor drive MLD type K are high-performance permanent magnets. Medical devices, such as pacemakers or hearing aids, can be destroyed or can cause malfunctions.

- Observe an adequate minimum distance to the secondary part if you have a pacemaker or use a hearing aid or other devices.



Danger to life due to electric shock.

Touching live parts can be deadly.

- Work on electrical installations or equipment may only be carried out by electricians according to electrical standards.

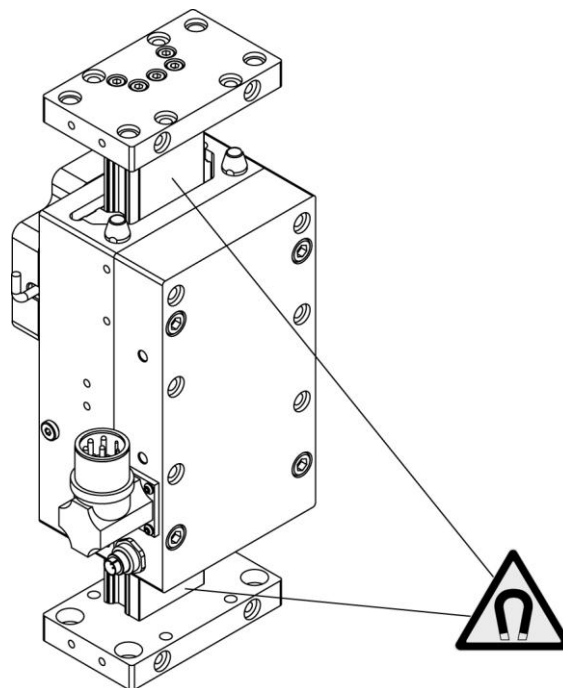


Figure 2: Magnetic area of linear motor drive MLD type K



During installation and commissioning, observe the technical data.

Notice For the technical data regarding

- Linear motor drive MLD type K
- Limit switches
- Reference switch
- Direct stroke measuring system

refer to the brochure: **Linear motor drive MLD type K**

7.2. Main components

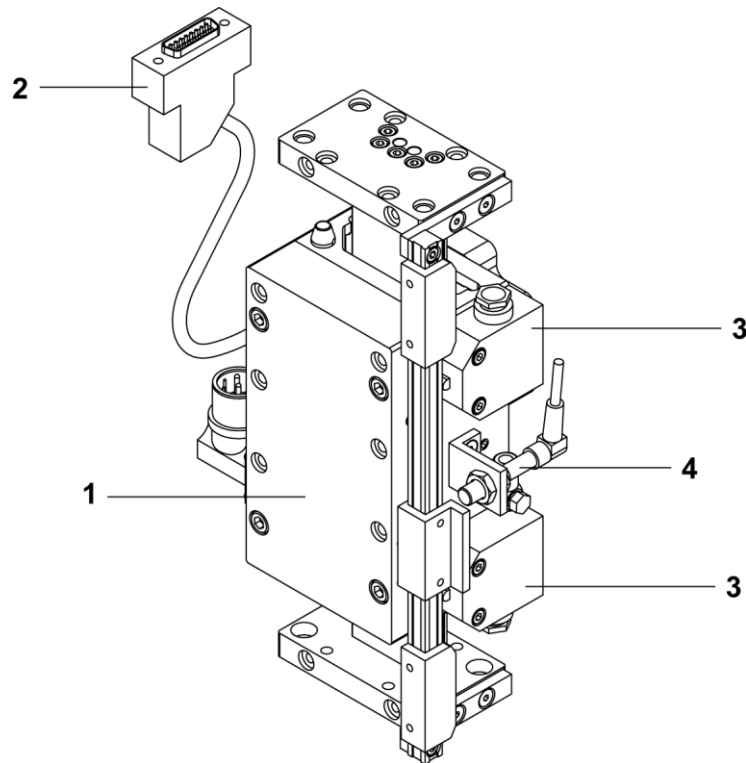


Figure 3: Main components of the linear motor drive MLD type K

- (1) Linear motor drive MLD 100 K
- (2) Direct stroke measuring system
- (3) Limit switches (optional)
- (4) Reference switch (optional)

7.3. Assembly of the linear motor drive



Danger of crushing due to uncontrolled movements.

- Only carry out work on the linear motor drive while the machine is shut off.
- Make sure that neither electric nor pneumatic energy is present at the linear motor drive.

The linear motor drives have multiple mounting surfaces for additional linear axes; these are mounted using adapter plates.

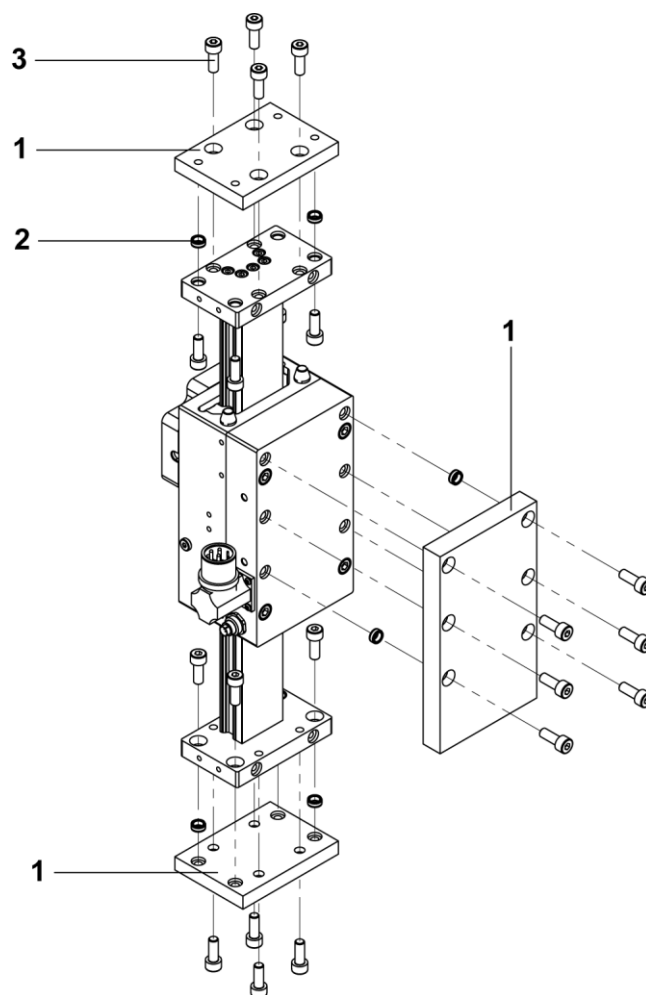


Figure 4: Mounting surfaces of the linear motor drive MLD type K

- (1) Adapter plate
- (2) Centering sleeve
- (3) Cylindrical screws

8. Repair

8.1. Module description

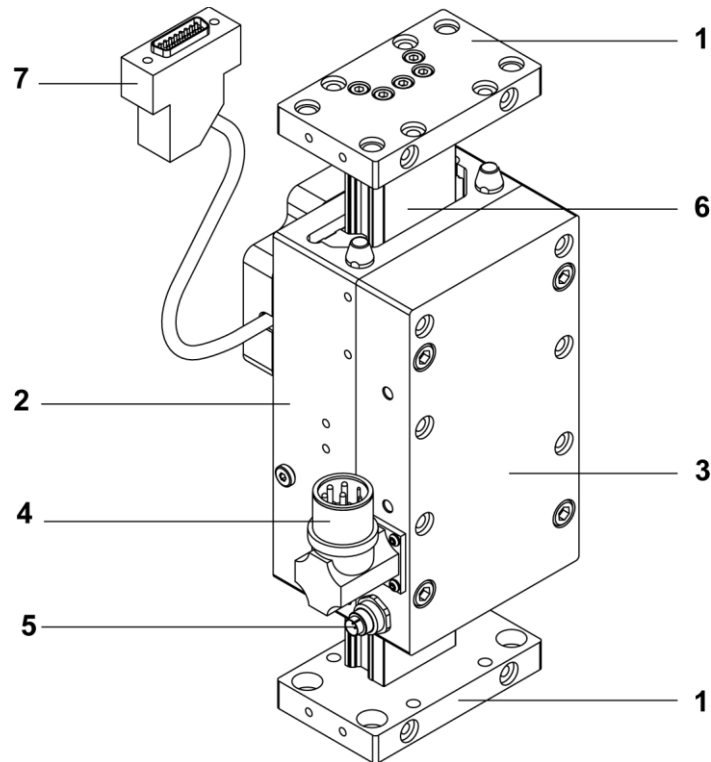


Figure 5: Module description of linear motor drive MLD type K

- (1) End plate
- (2) Guided slide
- (3) Motor housing
- (4) Motor connector
- (5) Hall sensor connector
- (6) Guide rail
- (7) Measuring system

8.2. Changing the motor housing



Notice

- During installation and commissioning, observe the technical data.
- As a general rule, all work on the drives and control units may be performed only while they are shut down. There must not be any electrical signals present.
- Allow the linear motor to cool down before starting any assembly or disassembly work.

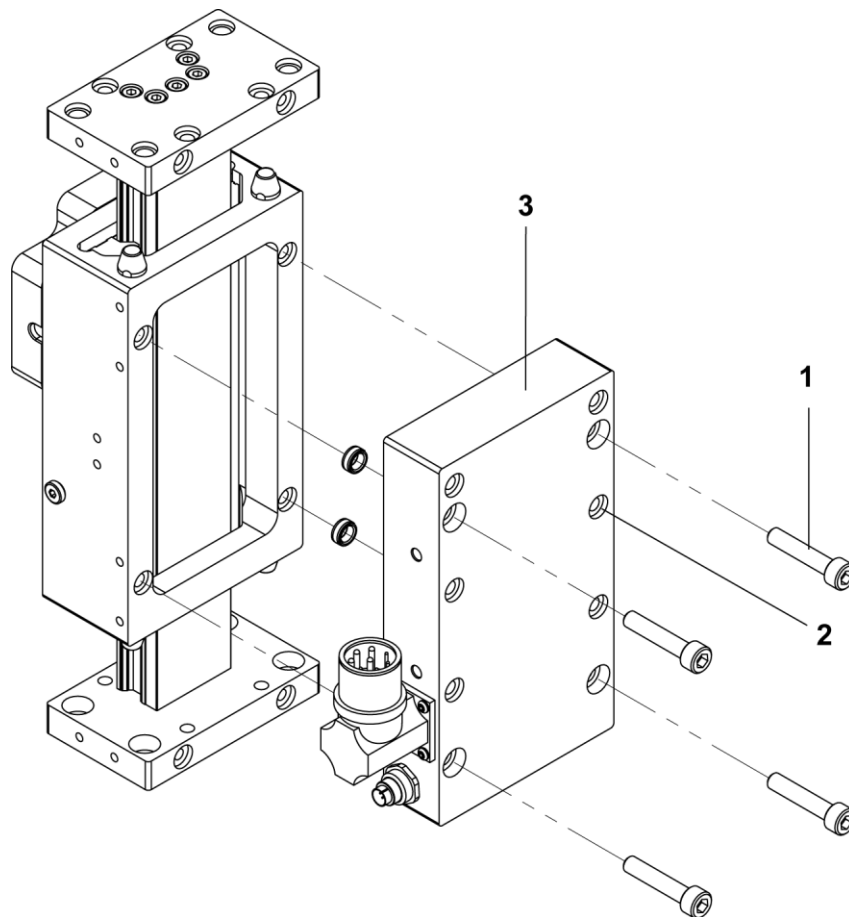


Figure 6: Changing the motor housing of a linear motor drive MLD type K

8.2.1. Uninstalling the motor housing

- Remove the screws (item 1).
- Using lifting screws M6x35 DIN 912 (item 2), lift the motor housing to bridge the magnetic force.
- Completely remove the motor housing (item 3).

8.2.2. Installing the motor housing

- Install the lifting screws (item 2).
(Let them protrude 5 mm.)
- Place the motor housing (item 3) on the guide rail.
- Slowly unscrew the lifting screws (item 2) one by one and set the motor housing onto the guided slide (item 4).
- Install the screws (item 1) (4x).



Never install the motor without lifting screws.
Danger of crushing!

8.3. Changing the roller shoes

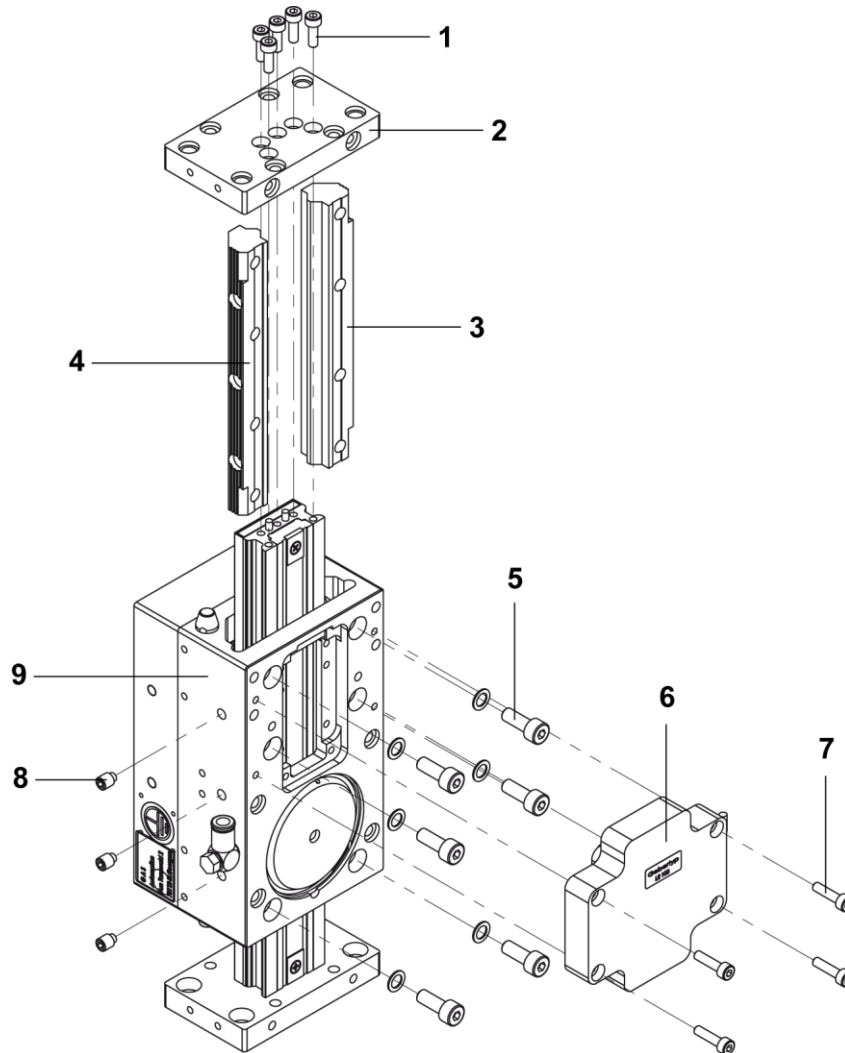


Figure 7: Change of roller shoes MLD 50/100 K

- (1) Cylindrical screws
- (2) End plate
- (3) Roller shoe, locating bearing side
- (4) Roller shoe, non-locating bearing side
- (5) Cylindrical screws
- (6) Cover
- (7) Cylindrical screws
- (8) Support screws
- (9) Guided slide

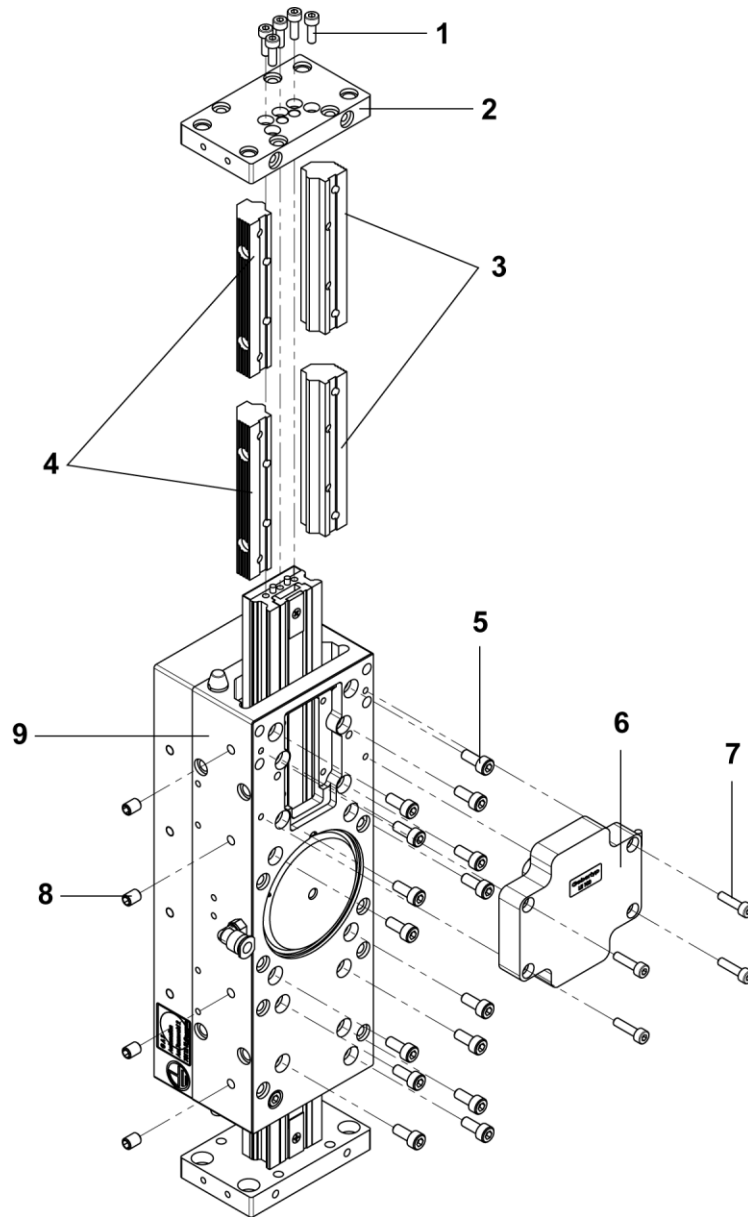


Figure 8: Change of roller shoes MLD 200 K

- (1) Cylindrical screws
- (2) End plate
- (3) Roller shoe, locating bearing side
- (4) Roller shoe, non-locating bearing side
- (5) Cylindrical screws
- (6) Cover
- (7) Cylindrical screws
- (8) Support screws
- (9) Guided slide



Due to the adjustment work required, the roller shoes should only be changed by specialist personnel.

Always exchange roller shoes as a pair.

8.3.1. Uninstalling the roller shoe – locating bearing side

- Unscrew the cylindrical screws (item 7) (4x) and remove the cover (item 6).
- Unscrew the cylindrical screws (item 1) (4x) and remove the end plate (item 2).
- Unscrew the cylindrical screws (item 5) and pull out the roller shoe (item 3).

8.3.2. Installing the roller shoe – locating bearing side

- Set the roller shoe (item 3) on the guided slide (item 9) and fasten it with the cylindrical screws and the lock washers (item 5). Secure the screws with locking liquid.



Make sure you are using the correct side: The locating bearing side is the side that does **not** have any threaded holes for roller shoe adjustment.

- The roller shoe must be mounted so that it is flush with the guided slide without gap. The screws must be tightened with 9 Nm.

8.3.3. Uninstalling the roller shoe – non-locating bearing side

- Uninstall the roller shoe on the locating bearing side (see chapter 8.3.1).
- Pull the guide rail out of the guided slide (item 9).
- Unscrew the cylindrical screws (item 5) and pull the roller shoe (item 4) out of the guide rail (item 9).

8.3.4. Installing the roller shoe – non-locating bearing side

- Install the roller shoe on the locating bearing side (see chapter 8.3.2).
- Set the roller shoe (item 4) on the guided slide (item 9) and loosely screw in the cylindrical screws and lock washers (item 5).



Make sure you are using the correct side: The non-locating bearing side is the side that does have threaded holes for roller shoe adjustment.

- Slide the guide rail into the guided slide (item 9).
- Mount the end plate (item 2) with the cylindrical screws (item 1) (4x).

8.3.5. Adjusting the roller shoe – non-locating bearing side

- Clamp the guided slide into a vise, with the non-locating bearing side facing up. Make sure you not to clamp the guided slide too tightly.
- Alternately tighten the support screws (item 8) until the guide rail runs without play in the guided slide.
- Next, secure the cylindrical screws (item 5) by unscrewing the screws one by one and securing each one with a lock washer and locking liquid. The screws must be tightened with 9 Nm.
- Alternately tighten the support screws (item 8) with 0.6 Nm until you cannot screw them in any further. Use locking liquid.
- Now the displacement force must be between 3 N and 6 N (without motor – if necessary, uninstall motor).

8.4. Changing the stroke measuring system



Due to the adjustment work required, the stroke measuring system should only be changed by specialist personnel.

Notice

8.4.1. Main components

Different measuring systems are used in the drives. This documentation describes two different measuring systems.

1. LE 100
2. LS 100

For more information on the optical and absolute stroke measuring systems, refer to the corresponding operating manuals.

The measuring systems LE 100 and LS 100 are non-contact incremental measuring systems. In connection with the measuring tape in the Schunk axes, the sensor head supplies a periodically recurring signal.

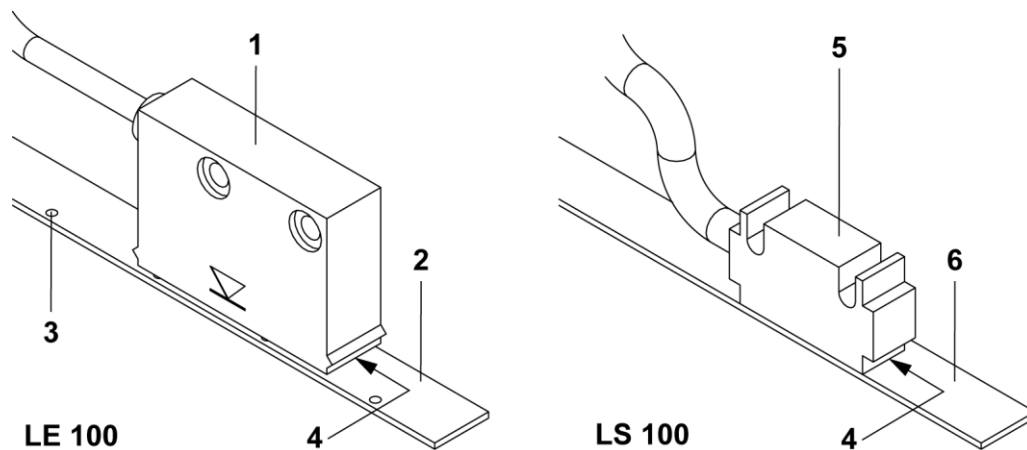


Figure 9: Measuring system modules

- (1) Reading head LE 100
- (2) Magnetic strip LE 100
- (3) Marking on magnetic strip
- (4) Distance between reading head and magnetic strip
- (5) Reading head LS 100
- (6) Magnetic strip LS 100

8.4.2. Changing the measuring system LE 100

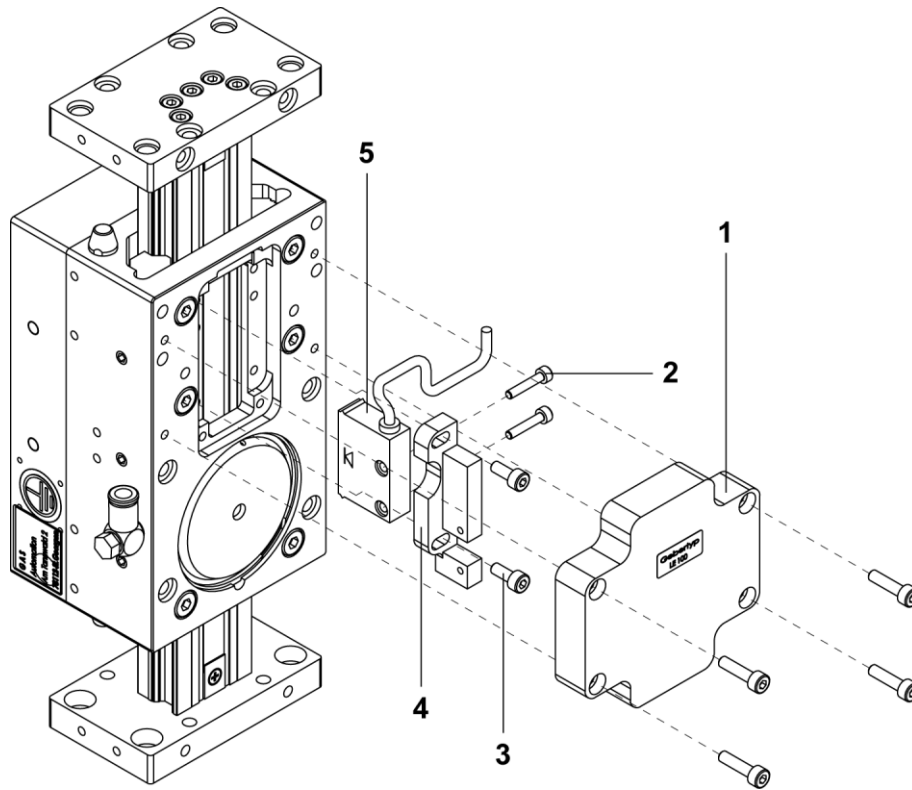


Figure 10: Measuring system LE 100

- (1) Cover
- (2) Cylindrical screws
- (3) Cylindrical screws
- (4) Reading head support
- (5) Reading head LE 100



The measuring system is precisely adjusted. In the event of a disassembly, the measuring system must be re-adjusted. Memorize the installation position of the reading head support. The cable must point in the same direction again.

- Remove the cover (item 1).
- Uninstall the reading head support (item 4).
- Remove the reading head (item 5) and replace it.



Special tool

Tester for measuring system LD including adapter cable (GAS order no. 323712).

Note

- Screw the reading head (item 5) to the reading head support (item 2).
- Screw the reading head support (item 4) into the recess on the slide. Ensure parallel position.
- The set and fastening screws on the reading head support with reading head have the following meaning:
- Use the measuring system tester to test the electric output signal of the reading head.
- Based on the result, you can calculate the distance between the ruler and the reading head. It must be 0.2 ± 0.05 mm along the entire length.
- If necessary, adjust the height.
- When the height is adjusted correctly, set the height adjustment using the screws (item 3).



Notice

When installing the reading head support complete with reading head, ensure the correct installation position. The markings on the reading head (1) and the ruler (2) must be on the same side.

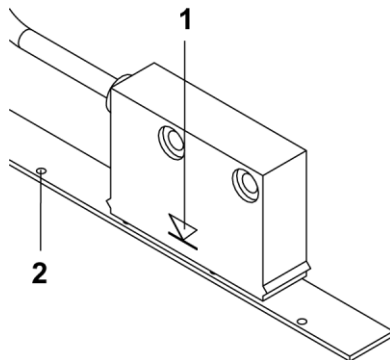


Figure 11: Markings on reading head and ruler LE 100



Notice

Because Schunk offers other stroke measuring systems in addition to the stroke measuring system described here, you must also observe the corresponding separate documentation.

8.4.3. Changing the measuring system LS 100

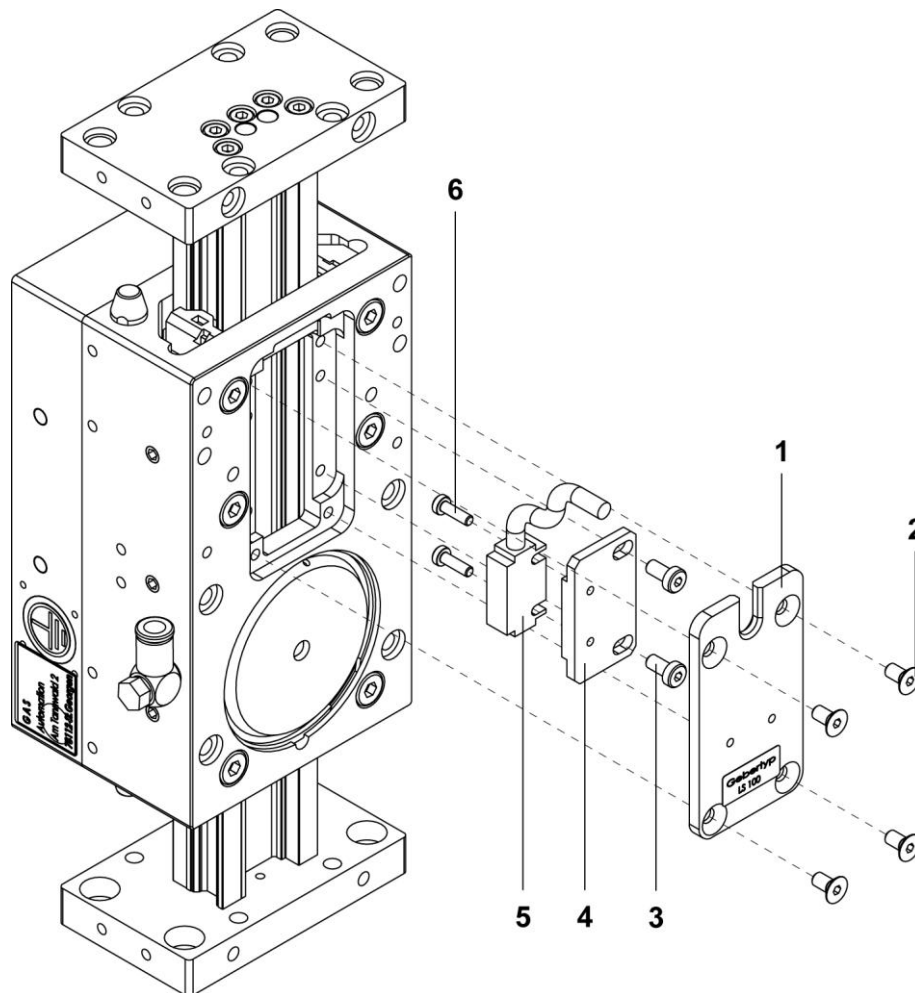


Figure 12: Measuring system LS 100

- (1) Cover
- (2) Screwing
- (3) Cylindrical screws
- (4) Reading head support
- (5) Reading head LS 100
- (6) Cylindrical screws



The measuring system is precisely adjusted. In the event of a disassembly, the measuring system must be re-adjusted. Memorize the installation position of the reading head support. The cable must point in the same direction again.

- Remove the cover (item 1).
- Uninstall the complete reading head support assembly (item 4).
- Remove the reading head (item 5) and replace it.



Special tool

**Tester for measuring system LD including adapter cable
(GAS order no. 323712).**

Note

- Screw the reading head (item 5) to the reading head support assembly (item 2).
- Screw the reading head support (item 4) into the recess on the slide. Ensure parallel position.
- The set and fastening screws on the reading head support with reading head have the following meaning:
- Use the measuring system tester to test the electric output signal of the reading head.
- Based on the result, you can calculate the distance between the ruler and the reading head. It must be 0.2 ± 0.05 mm along the entire length.
- If necessary, adjust the height.
- When the height is adjusted correctly, set the height adjustment using the screws (item 3).



Notice

When installing the reading head support complete with reading head, ensure the correct installation position.



Notice

Because Schunk offers other stroke measuring systems in addition to the stroke measuring system described here, you must also observe the corresponding separate documentation.

8.5. Changing the ruler LE 100

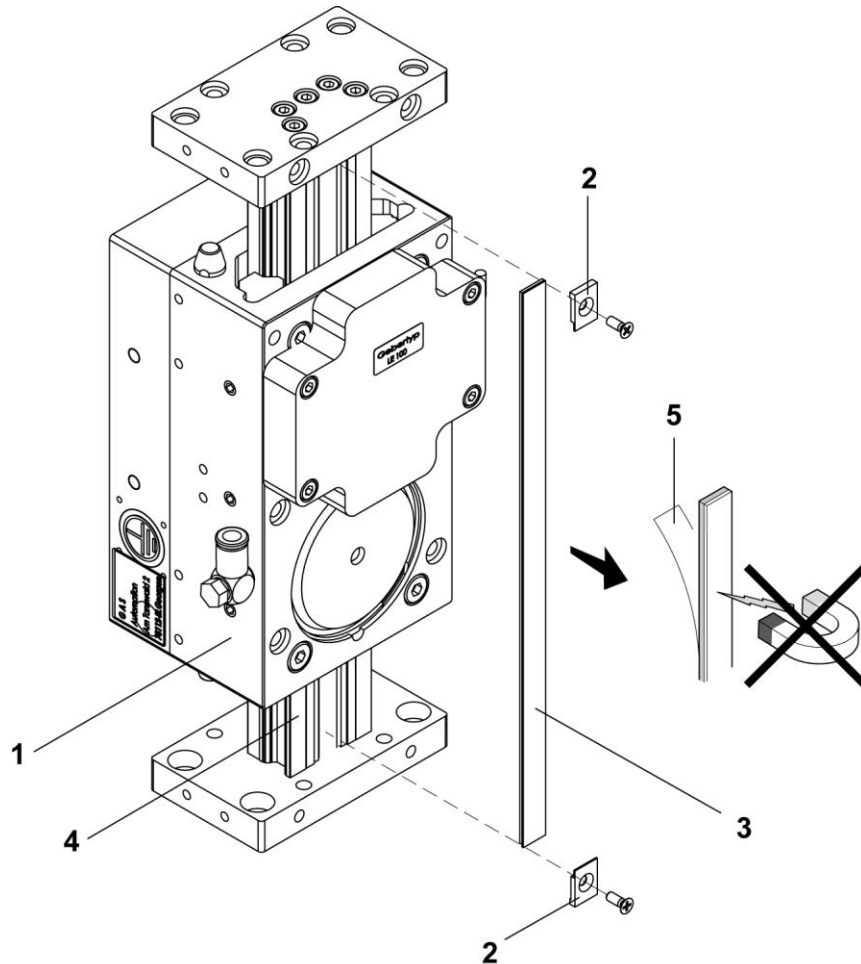


Figure 13: Changing the ruler LE 100

- (1) Guided slide
- (2) Ruler clamping
- (3) Ruler
- (4) Guide rail
- (5) Protective film



The magnetic strip of the measuring system must not be exposed to a strong magnetic field. At about 30 gauss or more, the magnetic strip encoding will be destroyed. Keep it away from the secondary part (permanent magnets) of the linear motor drive.

- Move the guided slide (item 1) to one side.
- Unscrew the ruler clamping (item 2) (2x).
- Carefully detach the ruler (item 3) from the guide rail (item 4) using a knife point and pull it off.
- Carefully clean the guide rail (item 4) of all adhesive residue using petroleum ether.
- Slide the ruler (item 3) underneath the guided slide (item 1) and place it on the guide rail (item 4).
- Length of the ruler (item 3) = length of the guide rail (item 4) - 24 mm.
- Lift up one side of the ruler (item 3) slightly and, using forceps, remove the protective film (item 5) from the adhesive film.
- While pulling off the protective film, press the ruler (item 3) onto the guide rail (item 4).
- When you are half-way done, slide the guided slide (item 1) to the opposite side.
- Fasten the ruler clamping (item 2) (2x).

8.6. Changing the ruler LS 100

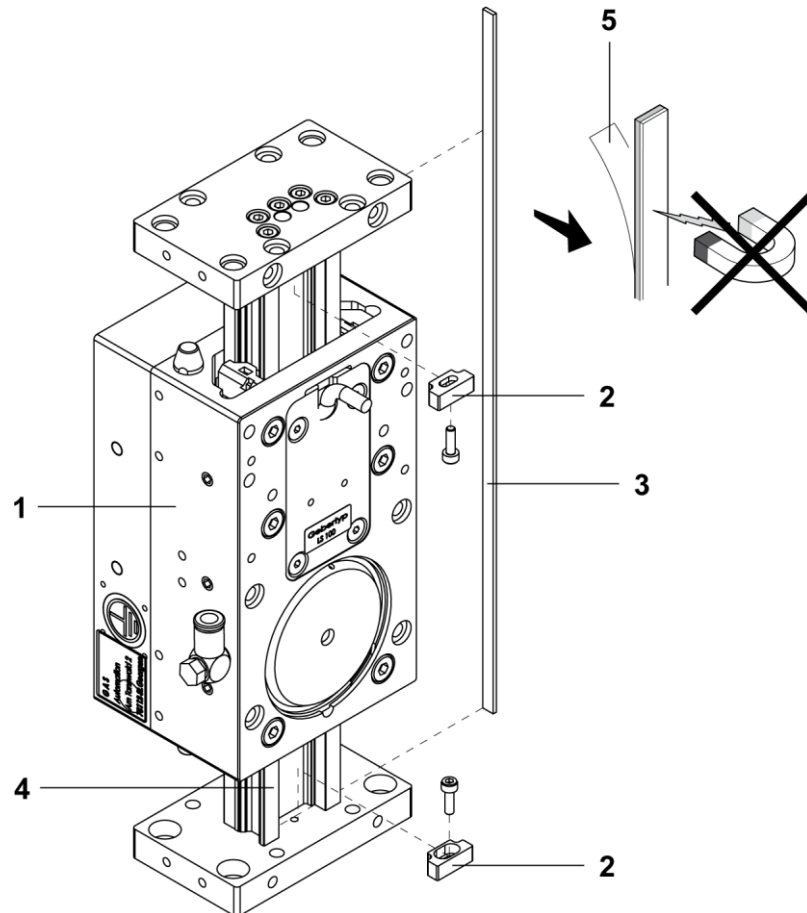


Figure 14: Changing the ruler LS 100 – gantry axis, installation position at bottom

- (1) Guided slide
- (2) Ruler clamping
- (3) Ruler
- (4) Guide rail
- (5) Protective film



The magnetic strip of the measuring system must not be exposed to a strong magnetic field. At about 30 gauss or more, the magnetic strip encoding will be destroyed. Keep it away from the secondary part (permanent magnets) of the linear motor drive.

- Move the guided slide (item 1) to one side.
- Unscrew the ruler clamping (item 2) (2x).
- Carefully detach the ruler (item 3) from the guide rail (item 4) using a knife point and pull it off.
- Carefully clean the guide rail (item 4) of all adhesive residue using petroleum ether.
- Slide the ruler (item 3) underneath the guided slide (item 1) and place it on the guide rail (item 4).
- Length of the ruler (item 3) = length of the guide rail (item 4), i.e. 2 mm.
- Lift up one side of the ruler (item 3) slightly and, using forceps, remove the protective film (item 5) from the adhesive film.
- While pulling off the protective film, press the ruler (item 3) onto the guide rail (item 4).
- When you are half-way done, slide the guided slide (item 1) to the opposite side.

8.7. Changing the wipers



When using wipers, it is especially important that you clean the guide strips and lubricate them with an oil-soaked cloth.

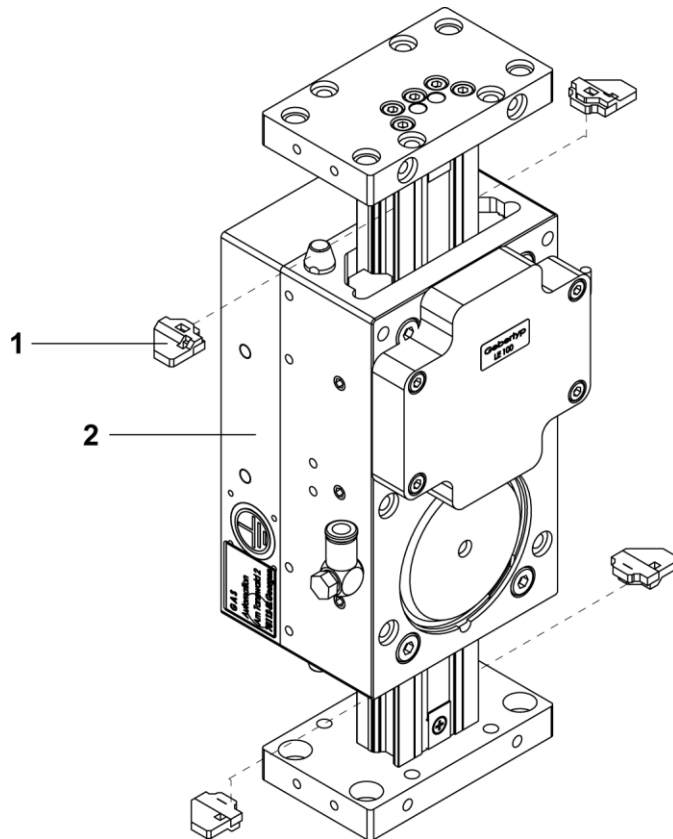


Figure 15: Changing the wipers

- (1) Wipers
- (2) Guided slide

- Slide the guided slide (item 1) to the center of the axis.
- The wipers (item 2) are attached to the front of the roller shoe by two snap-fits.
- Lever out the wipers (e.g. using a screwdriver) at the notch on the snap-fits.
- To reinstall, press the wipers with the snap-fits into the opening provided on the roller shoe.

8.8. Replacing the brake piston



**Switch off controller and compressed air.
The brake piston is pre-loaded with disk springs.**

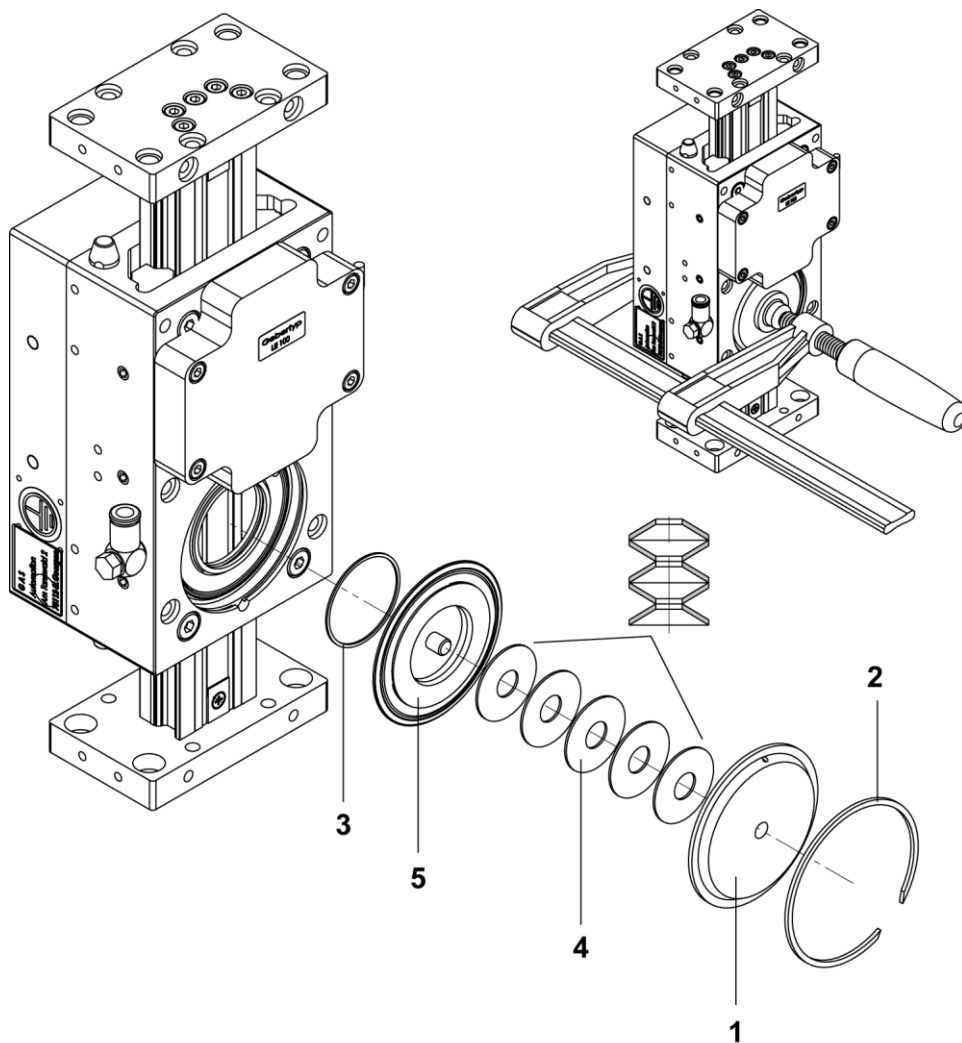


Figure 16: Replacing the brake piston

- (1) Brake cover
- (2) Retaining ring
- (3) O-ring
- (4) Disk springs
- (5) Brake piston

8.8.1. Uninstalling the brake piston

- Using a vise, clamp the brake cover (item 1).
- Remove the retaining ring (item 2).
- Slowly loosen the vise.
- Remove the brake cover (item 1), O-ring (item 3) and disk springs (item 4).
- Using pliers (with braces), pull out the brake piston (item 5).

8.8.2. Installing the brake piston

- Slightly grease and insert the O-ring (item 3).
- Insert the brake piston (item 5) and fit the membrane into place.
- Fit the disk springs (item 4) and the brake cover (item 1).



Notice

When installing the disk springs (item 4), make sure the individual disk springs are placed in the correct position.

- Set the vise onto the brake cover (item 1) and press in the cover.
- Install the retaining ring (item 2).
- Loosen and remove the vise.



Warning

Proper functioning of the emergency holding brake can only be ensured if the following notes are observed:

- **Only move the guide or the slide with the brake released.**
- **Keep the brake surfaces clean and free from oil.**
- **Only the running surfaces may be lightly oiled with GAS special oil.**

8.9. Limit switches and reference switches

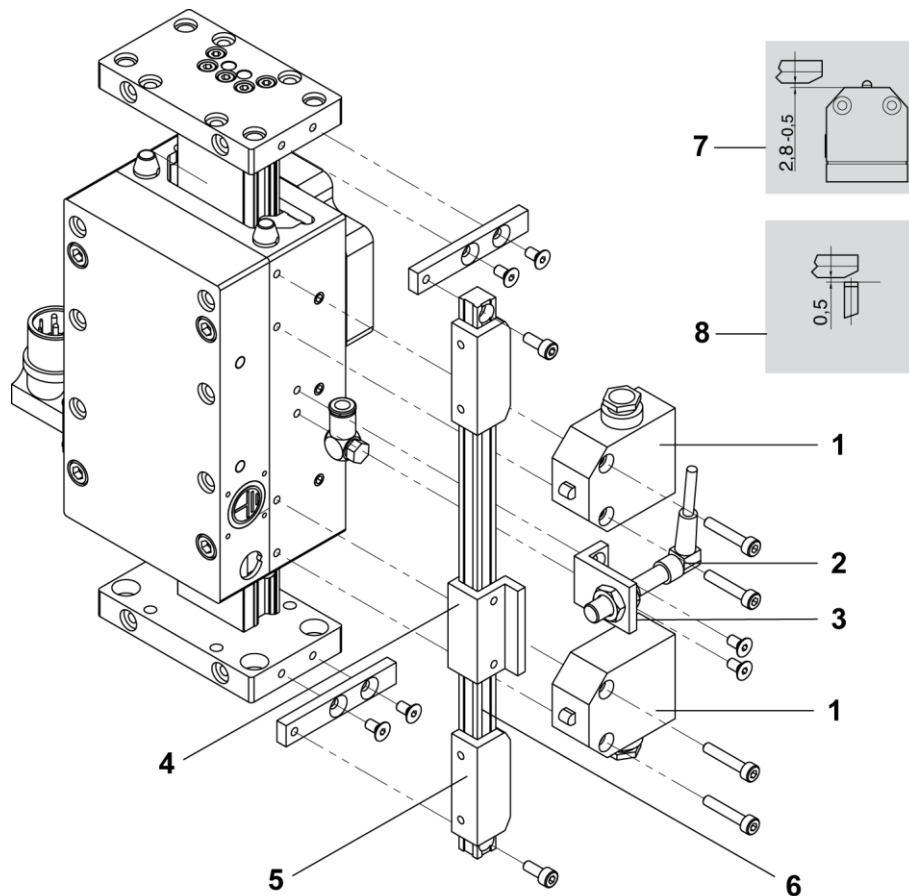


Figure 17: Mechanical limit switches and inductive reference switch

- (1) Limit switches, mechanical
- (2) Reference switch, inductive
- (3) Bracket for reference switch
- (4) Cam for reference switch
- (5) Cam for limit switch
- (6) Switch rod
- (7) Switching distance, mechanical limit switch
- (8) Switching distance, inductive reference switch

9. Electrical interfaces

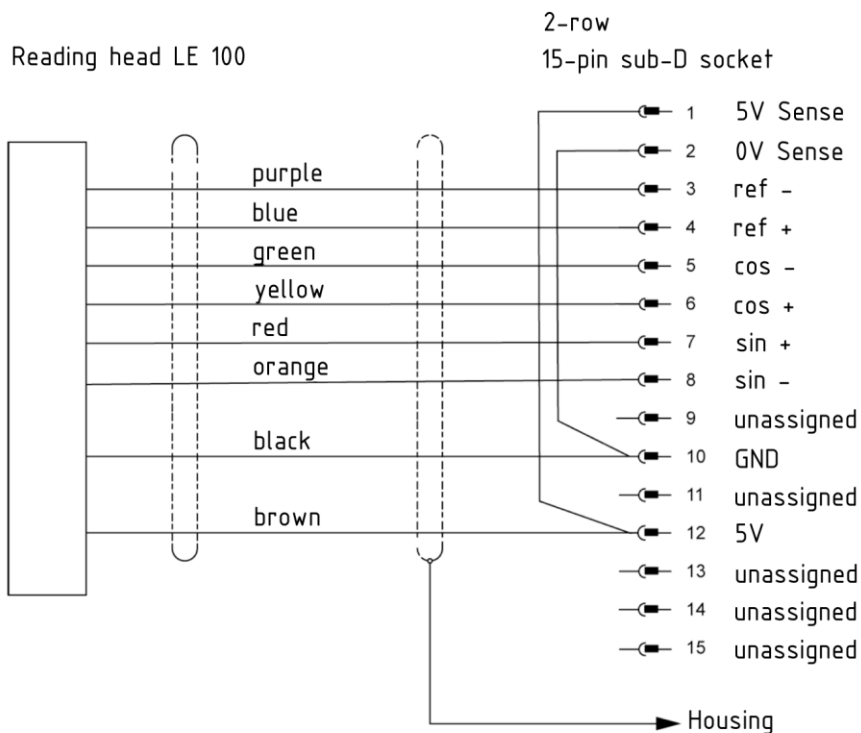
9.1. Measuring systems

9.1.1. Technical data

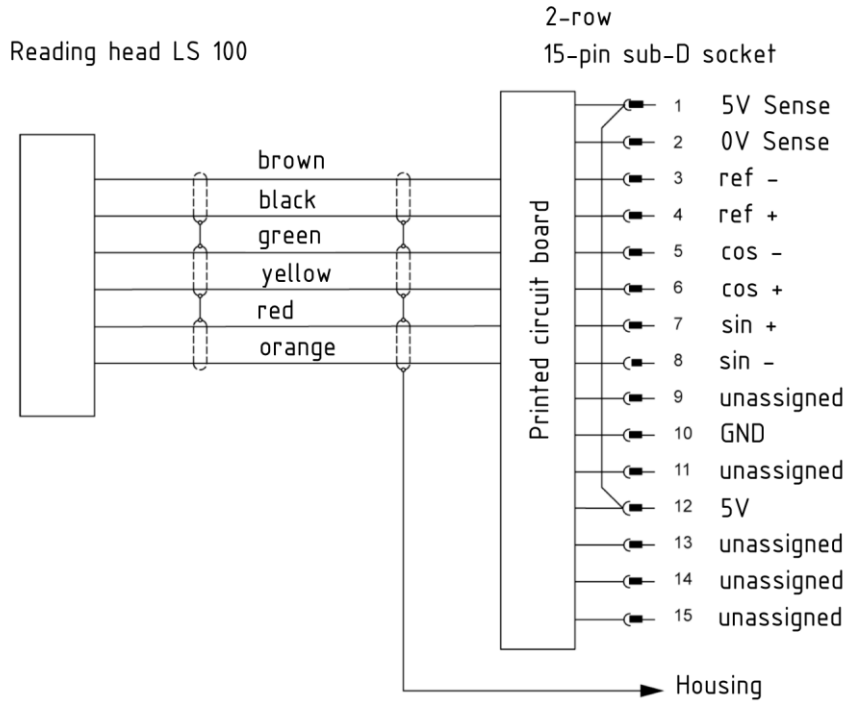
Description		LE 100	LS 100
Operating voltage	(VDC)	5 ± 5%	5 ± 5%
Output signal		Sin, Cos, Sin, Cos	Sin, Cos, Sin, Cos
Signal amplitude	(Vss)	1 ±10%	1 ±10%
Offset sine/cosine	(V)	2.5 ±0.5%	2.5 ±0.5%
Signal period	(µm)	1000	1000
Reference signal, periodic	(mm)	20	1*
Distance reading head – measuring tape (incl. covering tape)	(mm)	0.2 ±0.05	0.2 ±0.05

*) With reference converter

9.1.2. Interfaces of measuring system LE 100

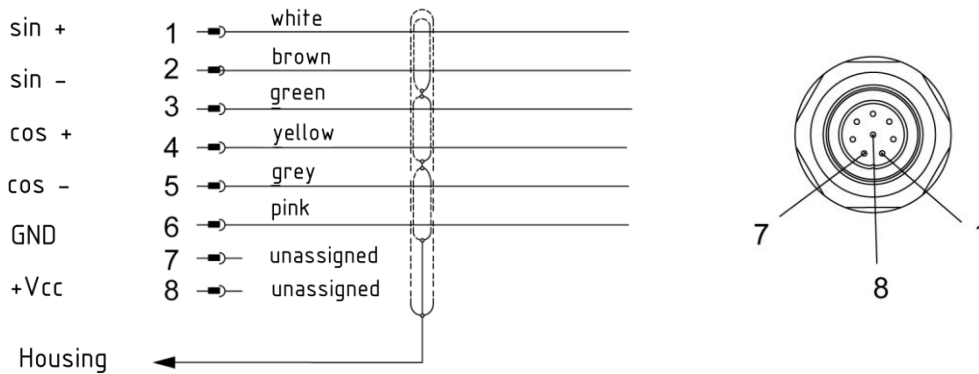


9.1.3. Interfaces of measuring system LS 100



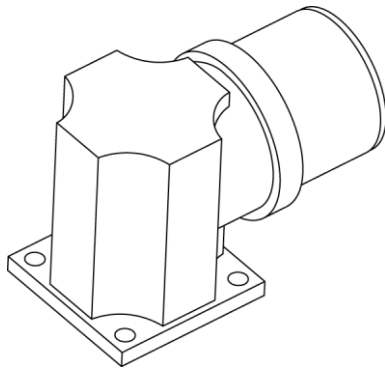
9.2. Hall sensors

8-pin socket
Series 712

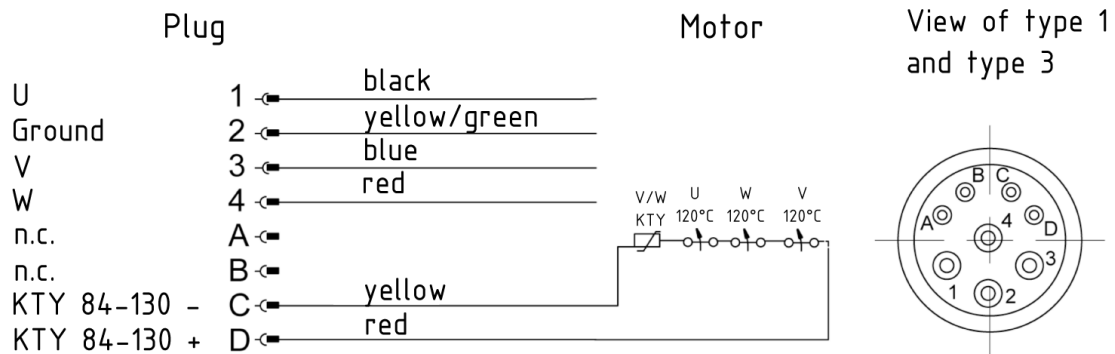
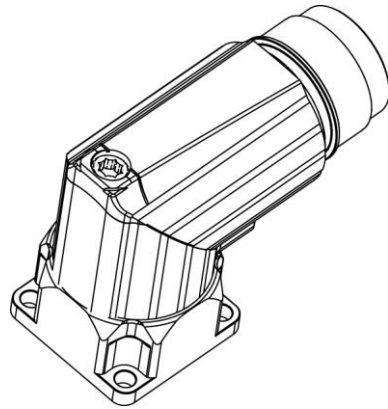


9.3. Motor

Type 1: Hypertac



Type 3: Interconnect



10. Maintenance and care



Only carry out work on linear motor drives while the machine is switched off.

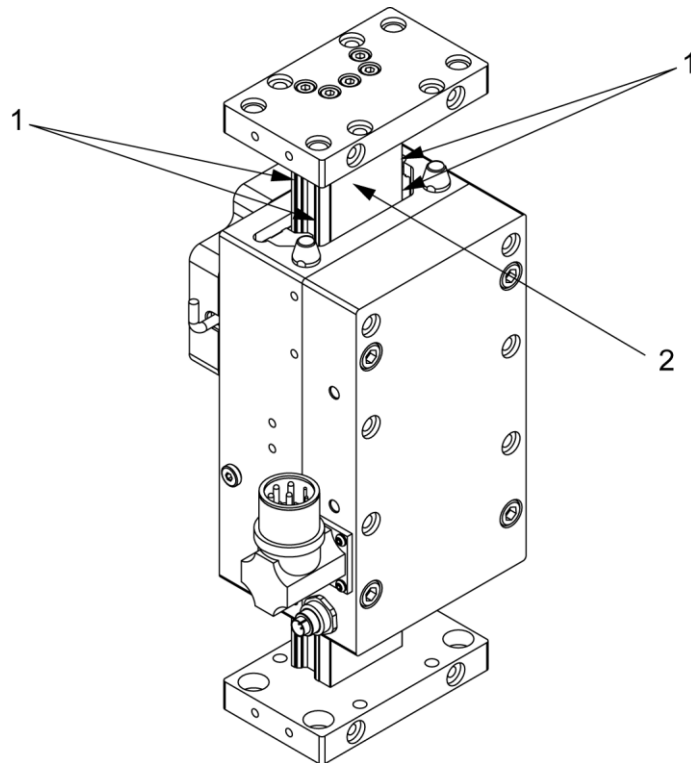


Figure 18: Maintenance of guide and secondary part

10.1. Preventive maintenance by the customer

To ensure the operational safety of the linear motor drive MLD type K over a long period of time, the operating personnel must carry out maintenance work in specific intervals.

10.1.1. Weekly maintenance (depending on degree of contamination)

- Rub the guide strips (item 1) with an oil-soaked cloth.

10.1.2. Every 2 to 4 weeks

- Clean the secondary part (item 2) with ethyl alcohol.

11. Accessories

Accessories from Schunk – the ideal components for the best functionality, reliability, and controlled production for all automation modules.

1	Centering sleeves	For precisely fitting connections between axes and
2	Inductive sensors	For end position control and reference measurement
3	Mechanical limit switches	For end position control
4	Connection cable for reference and limit switches	All required connection cables
5	Shock absorber	For supporting the masses in case of system failures
6	Wipers	For wiping the tracks during operation
7	Cable tracks	Safe energy supply with moving actuators
8	Holding brake	Pneumatic standstill brake for controller relief and for vertical applications
9	Pneumatic switching valve	For controlling the holding brake
10	Cable sets	Various cable sets and cable lengths for different controller types and distances
11	Commissioning tools	Start-up software, programming cable and commissioning instructions for controllers
12	Drive controllers and control units	Proven and approved components for your application scenario

For more detailed information, refer to the main catalog.

12. Spare parts

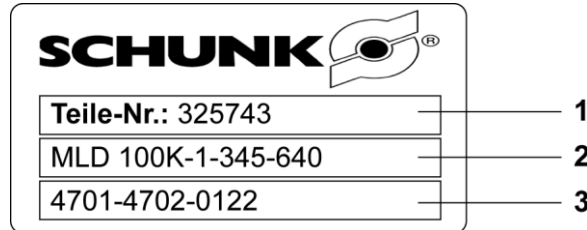


Figure 19: Nameplate

12.1. Note regarding spare part orders

Our products are always subject to technical modification and improvement. To avoid incorrect deliveries, and to order parts without a part number, always provide the information specified on the nameplate as well as the serial number of the linear motor drive.

The nameplate (Figure 23) is located on the guide rail.

Example:

- (1) Part no. – item number
- (2) Axis designation MLD 100 K with number of slides – useful stroke – profile length
- (3) Options

12.2. Note regarding the spare parts and wearing parts list

Remark:

- | | |
|---|---------------------------|
| S | Only with optional switch |
| H | Stroke-dependent |
| R | Cleaning agent |
| E | End position dampening |

12.3. Axes

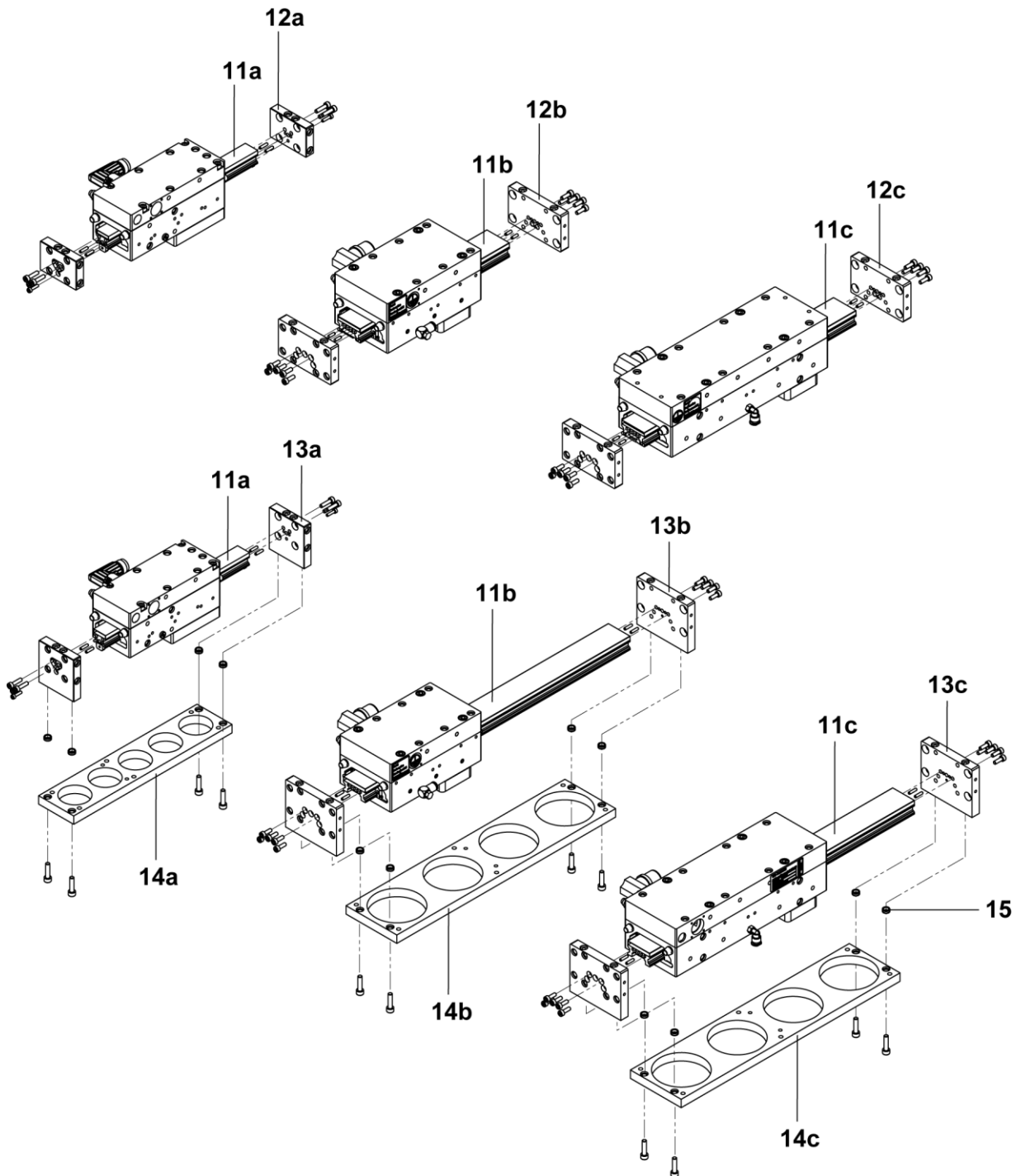


Figure 20: Spare parts – axis type K

Item	Type of axis	Designation	Quantity	Option	GAS order no.
11a	MLD 50 K(T)	Profile guide	1	H	344 291
11b	MLD 100	Profile guide	1	H	328 352
11c	MLD 200	Profile guide	1	H	328 352
12a	MLD 50 K	End plate	2		333 705
12b	MLD 100 K	End plate	2		329 786
12c	MLD 200 K	End plate	2		329 786
13a	MLD 50 KT	End plate	2		333 708
13b	MLD 100 KT	End plate	2		344 345
13c	MLD 200 KT	End plate	2		344 345
14a	MLD 50 KT	Table top	1	H	336 012
14b	MLD 100 KT	Table top	1	H	333 936
14c	MLD 200 KT	Table top	1	H	333 936
15	All	Centering sleeves	4		301 587
16	All	Ethyl alcohol 50 ccm	1	R	301 480
17	All	Oil 50 ccm	1	R	301 478
18	All	Measuring system tester	1		323 712
19	All	Documentation Commissioning of Indradrive (German/English) including CD-ROM	1		315 016

12.4. Motors

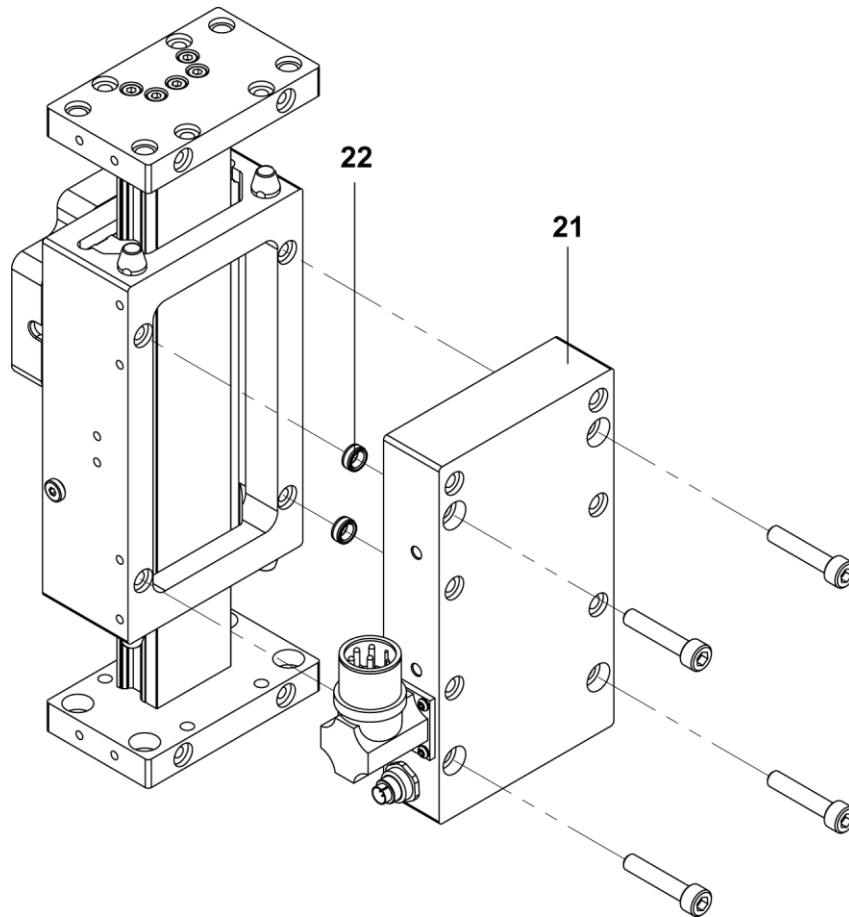
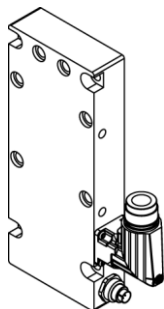


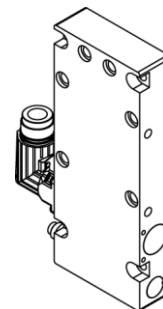
Figure 21: Spare parts – motors

Motor variants MLD 50 K(T):

Variant 1: Linear motor RS

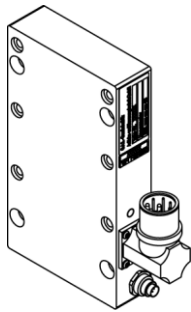


Variant 2: Linear motor LS

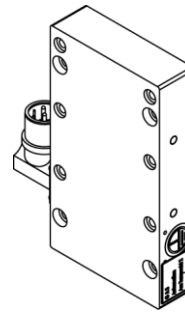


Motor variants MLD 100 K(T):

Variant 3: Linear motor RS

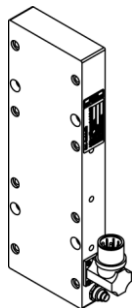


Variant 4: Linear motor LS

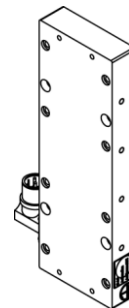


Motor variants MLD 200 K(T):

Variant 4: Linear motor RS



Variant 5: Linear motor LS





Motors without Hall sensor

Item	Type of axis	Designation	Quantity	Variant	GAS order no.
20	MLD 50 K(T)	Linear motor MLS 05-85-15 LS	1	2	352 564
	MLD 50 K(T)	Linear motor MLS 05-85-15 RS	1	1	352 565
	MLD 100 K(T)	Linear motor MLS 10-85-25 LS	1	4	336 142
	MLD 100 K(T)	Linear motor MLS 10-85-25 RS	1	3	333 869
	MLD 200 K(T)	Linear motor MLS 20-85-15 LS	1	6	332 475
	MLD 200 K(T)	Linear motor MLS 20-85-15 RS	1	5	333 868
21	All	Centering sleeve Ø 9	6		301 587

Motors with Hall sensor

Item	Type of axis	Designation	Quantity	Option	Variant	GAS order no.
20	MLD 50 K(T)	Linear motor MLS 05-85-15 LS	1		2	332 647
	MLD 50 K(T)	Linear motor MLS 05-85-15 RS	1		1	329 354
	MLD 100 K(T)	Linear motor MLS 10-85-25 LS	1		4	325 753
	MLD 100 K(T)	Linear motor MLS 10-85-25 RS	1		3	325 754
	MLD 200 K(T)	Linear motor MLS 20-85-15 LS	1		6	325 743
	MLD 200 K(T)	Linear motor MLS 20-85-15 RS	1		5	325 742
21	All	Centering sleeve Ø 9	6			301 587

12.5. Guide

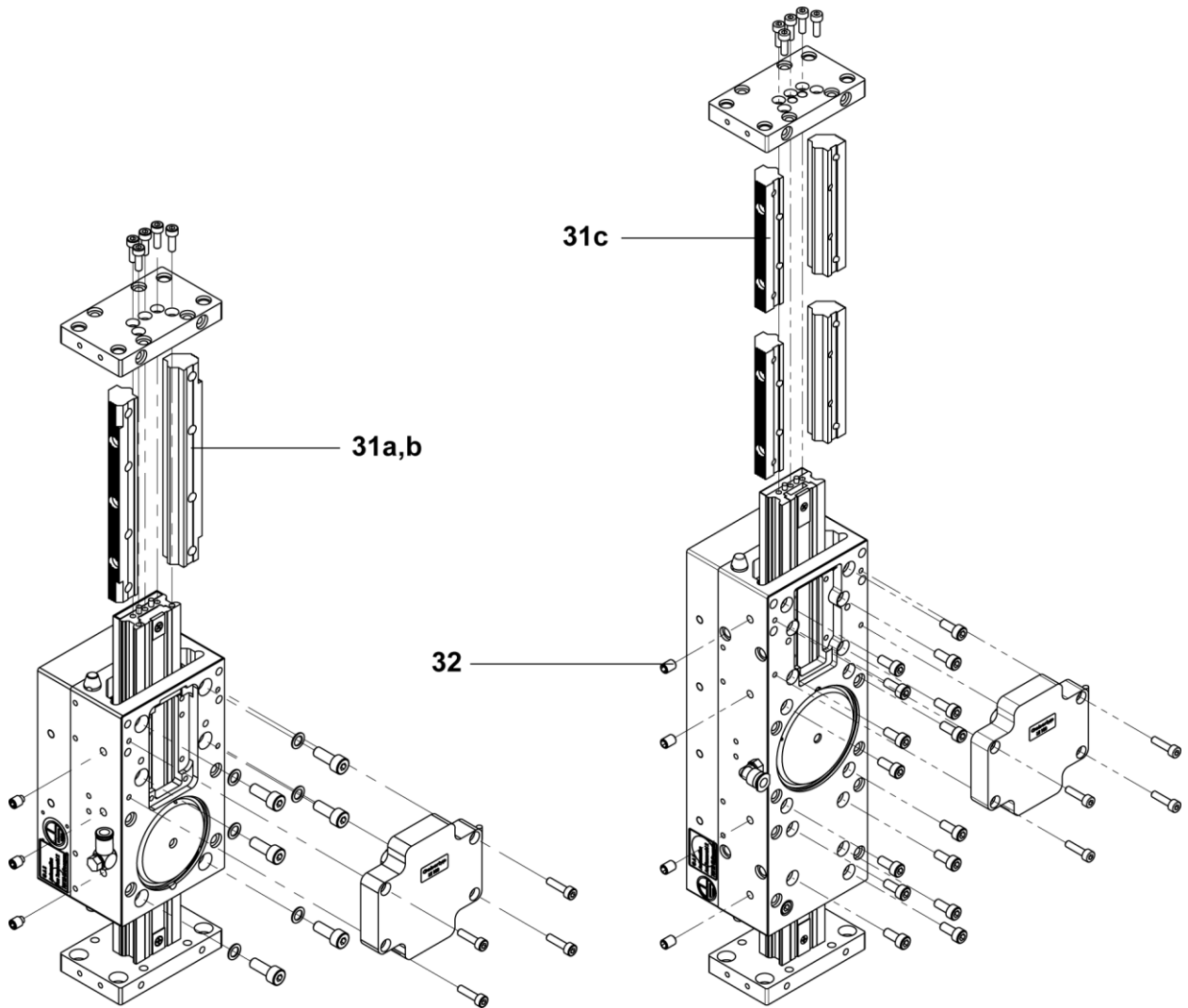


Figure 22: Spare parts – guide

Item	Type of axis	Designation	Quantity	GAS order no.
31a	MLD 50 K(T)	Roller shoes	2	329 765
31b	MLD 100 K(T)	Roller shoes	2	329 765
31c	MLD 200 K(T)	Roller shoes	4	332 796
32a	MLD 50 K(T)	Support screws	3	336 083
32b	MLD 100 K(T)	Support screws	3	329 766
32c	MLD 200 K(T)	Support screws	4	329 766

12.6. Measuring system

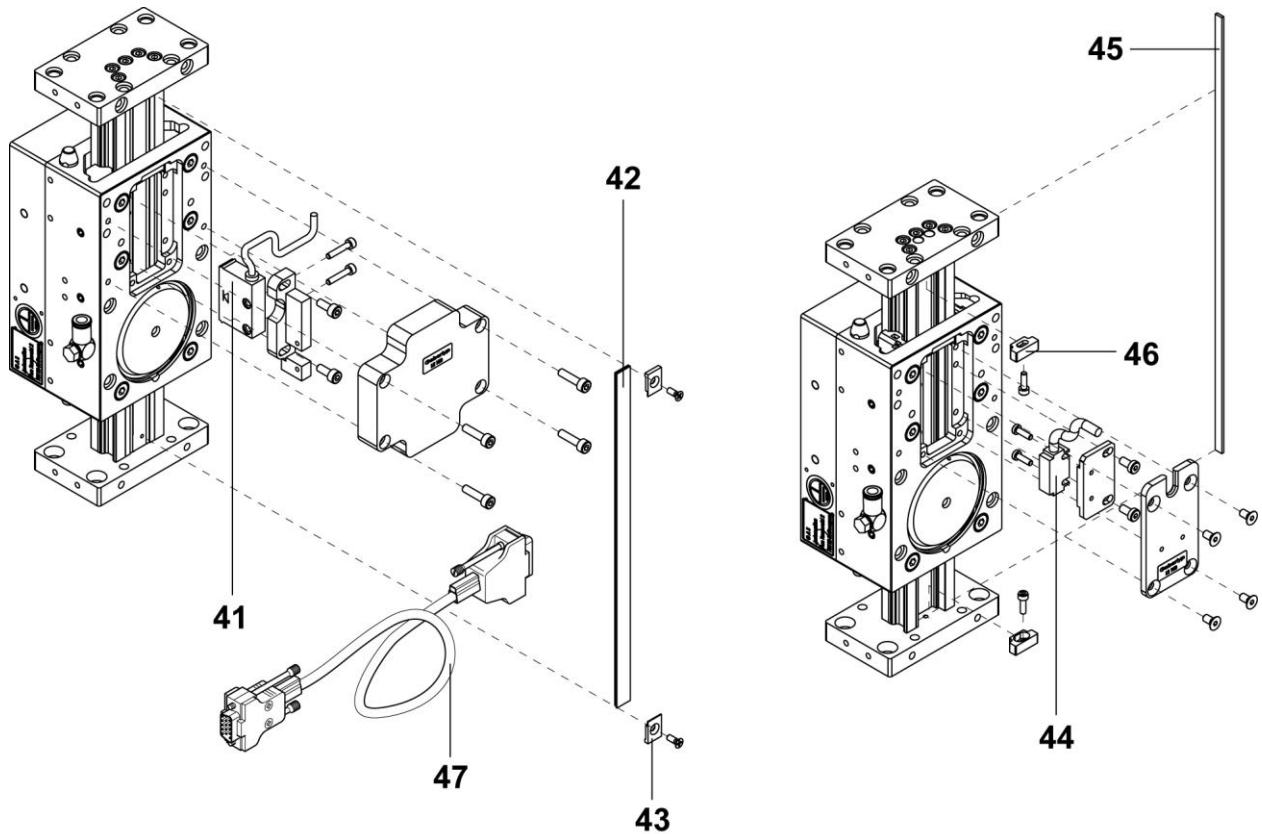


Figure 23: Spare parts – measuring system LE 100 / LS 100

Item	Type of axis	Designation	Quantity	Option	GAS order no.
41a	All	Reading head LE100 5 m	1		336 025
41b		Reading head LE100 10 m	1		341 782
42	All	Ruler LE100	1	H	346 611
43	All	Ruler clamping	2		345 914
44a	All	Reading head LS100 5 m	1		319 285
44b		Reading head LS100 10 m	1		323 292
45		Ruler LS100	1	H	325 964
46	All	Ruler clamping	2		326 871
47	All	Reference pulse cable LS100	1		323 160

12.7. Holding brake

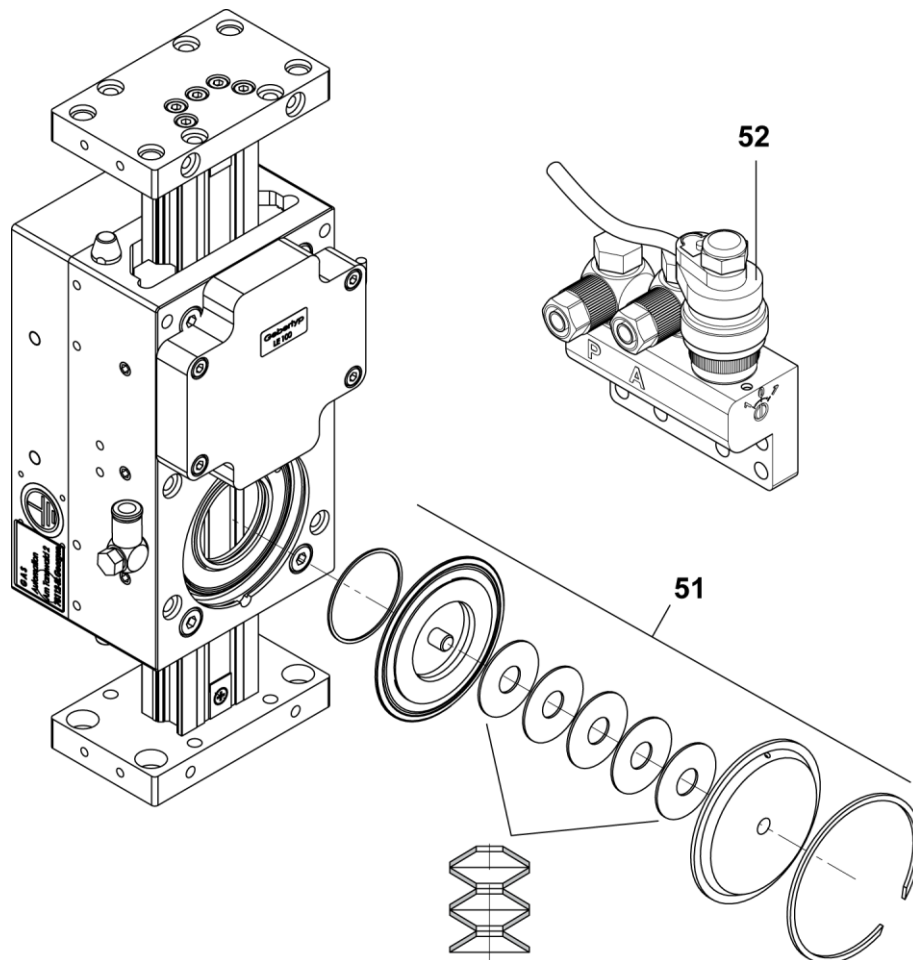


Figure 24: Spare parts – brake

Item	Type of axis	Designation	Quantity	GAS order no.
51a	LD 50 K	Installation set for pneumatic emergency stop brake	1	332 390
51b	LD 100 K	Installation set for pneumatic emergency stop brake	1	342 570
51c	LD 200 K	Installation set for pneumatic emergency stop brake	1	342 546
52	All	Brake valve, 10 m cable (GAS)	1	337 784
53	All	Brake valve, 10 m cable (Festo)	1	325 593

12.8. Accessories

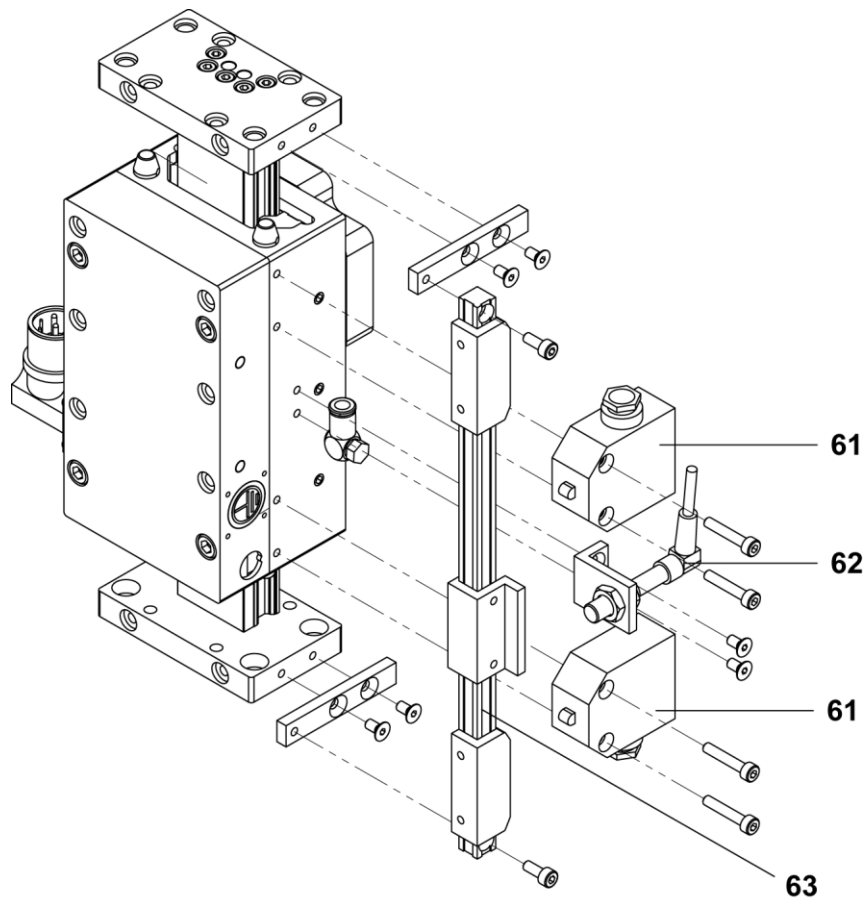


Figure 25: Spare parts – accessories

Item	Type of axis	Designation	Quantity	GAS order no.
61	All	Mechanical limit switch	2	308 190
62	All	Inductive limit switch	2	312 586
63	All	Inductive reference switch PNP	1	306 182
64	All	Inductive reference switch NPN	1	318 432

13. EC declaration of incorporation

In terms of the EC Machinery Directive 2006/42/EC, annex II B

Manufacturer/ distributor SCHUNK GmbH & Co. KG.
Spann- und Greiftechnik
Bahnhofstr. 106 – 134
74348 Lauffen/Neckar, Germany

We hereby declare that the following product:

Product designation: Linearantrieb
Type designation: K, KT
ID number: -

meets the applicable basic requirements of the Directive **Machinery (2006/42/EC)**.

The incomplete machine may not be put into operation until conformity of the machine into which the incomplete machine is to be installed with the provisions of the Machinery Directive (2006/42/EC) is confirmed.

Applied harmonized standards, especially:

EN ISO 12100-1 Safety of machines - Basic concepts, general principles for design -- Part 1:
Basic terminology, methodology
EN ISO 12100-2 Safety of machines - Basic concepts, general principles for design -- Part 2:
Technical principles

The manufacturer agrees to forward on demand the special technical documents for the incomplete machine to state offices.

The special technical documents according to Annex VII, Part B, belonging to the incomplete machine have been created.

Person responsible for documentation: Mr. Michael Eckert, Tel.: +49(0)7133/103-2204

Location, date/signature: Lauffen, Germany,
January 2010
Title of the signatory Director for Development

p.p. 

14. Contact



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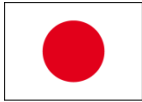
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